



14.1 Overview

Helical-geared precision right-angle planetary geared motors

Technical data

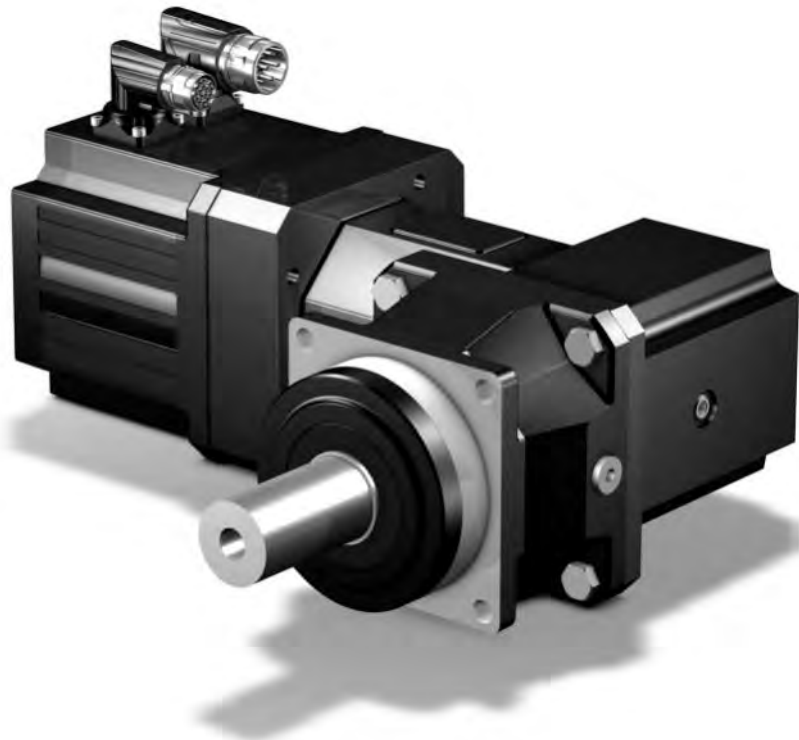
i	3 – 210
M_{2acc}	11 – 3000 Nm
$\Delta\varphi_2$	4 – 8.5 arcmin
η	≤ 94 – 96 %

Features

Power density	★★★★☆
Backlash	★★★★☆
Price category	€€€
Shaft load	★★★★☆
Smooth operation	★★☆☆☆
Torsional stiffness	★★★★☆
Mass moment of inertia	★★☆☆☆
Helical gearing	✓
Maintenance-free	✓
Small installation space	✓
Continuous operation without cooling (FKM sealing ring at the input)	✓
Reinforced output bearing	✓ (optional)
Compact and highly dynamic due to direct motor attachment	✓

PKX

Key: ★☆☆☆☆ good | ★★★★★ excellent





14.2 Selection tables

The technical data specified in the selection tables applies to:

- Installation altitudes up to 1000 m above sea level
- Surrounding temperatures from 0 °C to 40 °C
- Drives with convection-cooled motors (e.g. EZ401U)

You can calculate the technical data for drives with forced ventilated motors (for example EZ401B) at <http://products.stoeber.de>.

Formula symbol	Unit	Explanation
a_{th}	–	Parameter for calculating $K_{mot,th}$
C_2	Nm/ arcmin	Torsional stiffness of gear unit (final stiffness) relative to the gear unit output
$\Delta\varphi_2$	arcmin	Backlash at the output shaft with a blocked input
η	%	Efficiency
i	–	Gear ratio
i_{exakt}	–	Mathematically exact gear ratio
J_1	$10^{-4}kgm^2$	Mass moment of inertia relative to the gear unit input
m	kg	Weight
$M_{2,0}$	Nm	Stall torque on the gear unit output
M_{2acc}	Nm	Maximum permitted acceleration torque on the gear unit output
$M_{2acc,max}$	Nm	Maximum permitted acceleration torque of a group of geared motors whose size and nominal torque n_{1N} are the same
M_{2N}	Nm	Nominal torque on the gear unit output (relative to n_{1N})
M_{2NOT}	Nm	Gear unit emergency-off torque on the gear unit output for max. 1000 load changes
$n_{1maxDBEL1,2,5,6}$	rpm	Maximum permitted input speed of the gear unit in continuous operation Installation positions EL1, EL2, EL5, EL6 (at surrounding temperature of 20 °C)
$n_{1maxDBEL3,4}$	rpm	Maximum permitted input speed of the gear unit in continuous operation Installation positions EL3, EL4 (at surrounding temperature of 20 °C)
n_{1maxZB}	min^{-1}	Maximum permitted input speed of the gear unit in cyclic operation (at surrounding temperature of 20 °C)
n_{1N}	min^{-1}	Nominal speed at the gear unit input
n_{2N}	min^{-1}	Nominal speed at the gear unit output
S	–	Load value: Quotient of gear unit and motor nominal torque without regard to the thermal performance limit. Represents a value for the reserve of the geared motor.



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14.2 Selection tables



n_{2N}	M_{2N}	$M_{2,0}$	a_{th}	S	Type	M_{2acc}	M_{2NOT}	i	i_{exakt}	n_{1max} DB EL1,2,5,6 [rpm]	n_{1max} DB EL3,4 [rpm]	n_{1max} ZB [rpm]	J_1 [10^{-4} kgm ²]	$\Delta\phi_2$ [arcmin]	C_2 [Nm/ arcmin]	m [kg]
P9KX ($n_{1N} = 2000$ rpm, $M_{2acc,max} = 3000$ Nm)																
57	1431	2165	279	1.4	P922_0350 KX801VF0010 MF EZ805U	3000	6000	35.00	35/1	1000	750	2000	215	4.5	327	128
63	1309	1979	152	1.5	P922_0160 KX801VF0020 MF EZ805U	3000	5530	32.00	32/1	1100	1100	2500	186	4.5	313	128
P9KX ($n_{1N} = 3000$ rpm, $M_{2acc,max} = 3000$ Nm)																
14	1454	1631	124	1.4	P922_0700 KX801VF0030 MF EZ701U	2700	5400	210.0	210/1	1300	1300	3000	52	4	315	90
20	1039	1165	89	1.9	P922_0500 KX801VF0030 MF EZ701U	2810	6000	150.0	150/1	1300	1300	3000	52	4	326	90
20	1684	2021	144	1.2	P922_0500 KX801VF0030 MF EZ702U	3000	6000	150.0	150/1	1300	1300	3000	57	4	326	93
25	831	932	71	2.4	P922_0400 KX801VF0030 MF EZ701U	2250	5530	120.0	120/1	1300	1300	3000	52	4.5	324	90
25	1347	1617	115	1.5	P922_0400 KX801VF0030 MF EZ702U	3000	5530	120.0	120/1	1300	1300	3000	57	4.5	324	93
29	727	816	62	2.8	P922_0350 KX801VF0030 MF EZ701U	1970	6000	105.0	105/1	1300	1300	3000	52	4.5	327	90
29	1179	1415	101	1.7	P922_0350 KX801VF0030 MF EZ702U	3000	6000	105.0	105/1	1300	1300	3000	58	4.5	327	93
29	1621	2044	139	1.2	P922_0350 KX801VF0030 MF EZ703U	3000	6000	105.0	105/1	1300	1300	3000	65	4.5	327	95
36	582	652	50	3.4	P922_0280 KX801VF0030 MF EZ701U	1570	5530	84.00	84/1	1300	1300	3000	52	4.5	326	90
36	943	1132	81	2.1	P922_0280 KX801VF0030 MF EZ702U	3000	5530	84.00	84/1	1300	1300	3000	58	4.5	326	93
36	1297	1635	111	1.5	P922_0280 KX801VF0030 MF EZ703U	3000	5530	84.00	84/1	1300	1300	3000	65	4.5	326	95
40	519	583	44	3.9	P922_0250 KX801VF0030 MF EZ701U	1400	6000	75.00	75/1	1300	1300	3000	53	4.5	324	90
40	842	1011	72	2.4	P922_0250 KX801VF0030 MF EZ702U	2880	6000	75.00	75/1	1300	1300	3000	58	4.5	324	93
40	1158	1460	99	1.7	P922_0250 KX801VF0030 MF EZ703U	3000	6000	75.00	75/1	1300	1300	3000	66	4.5	324	95
40	1495	2119	128	1.3	P922_0250 KX801VF0030 MF EZ705U	3000	6000	75.00	75/1	1300	1300	3000	78	4.5	324	100
50	415	466	36	4.8	P922_0200 KX801VF0030 MF EZ701U	1120	6000	60.00	60/1	1300	1300	3000	54	4.5	319	90
50	674	808	58	3.0	P922_0200 KX801VF0030 MF EZ702U	2300	6000	60.00	60/1	1300	1300	3000	59	4.5	319	93
50	926	1168	79	2.2	P922_0200 KX801VF0030 MF EZ703U	3000	6000	60.00	60/1	1300	1300	3000	67	4.5	319	95
50	1196	1696	102	1.7	P922_0200 KX801VF0030 MF EZ705U	3000	6000	60.00	60/1	1300	1300	3000	79	4.5	319	100
50	1252	2083	107	1.6	P922_0200 KX801VF0030 MF EZ802U	3000	6000	60.00	60/1	1300	1300	3000	103	4.5	319	109



14.3 Dimensional drawings

In this chapter you can find the dimensions of the geared motors.

There is a dimensional drawing for every possible shaft/housing design, each with the tables for gear unit dimensions, motor dimensions and geared motor dimensions.

Dimensions can exceed the specifications of ISO 2768-mK due to casting tolerances or accumulation of individual tolerances.

We reserve the right to make dimensional changes due to ongoing technical development.

You can download CAD models of our standard drives at <http://cad.stoeber.de>.

Combination options and the dimensions of forced ventilated geared motors can be found at <http://cad.stoeber.de>.

Tolerances

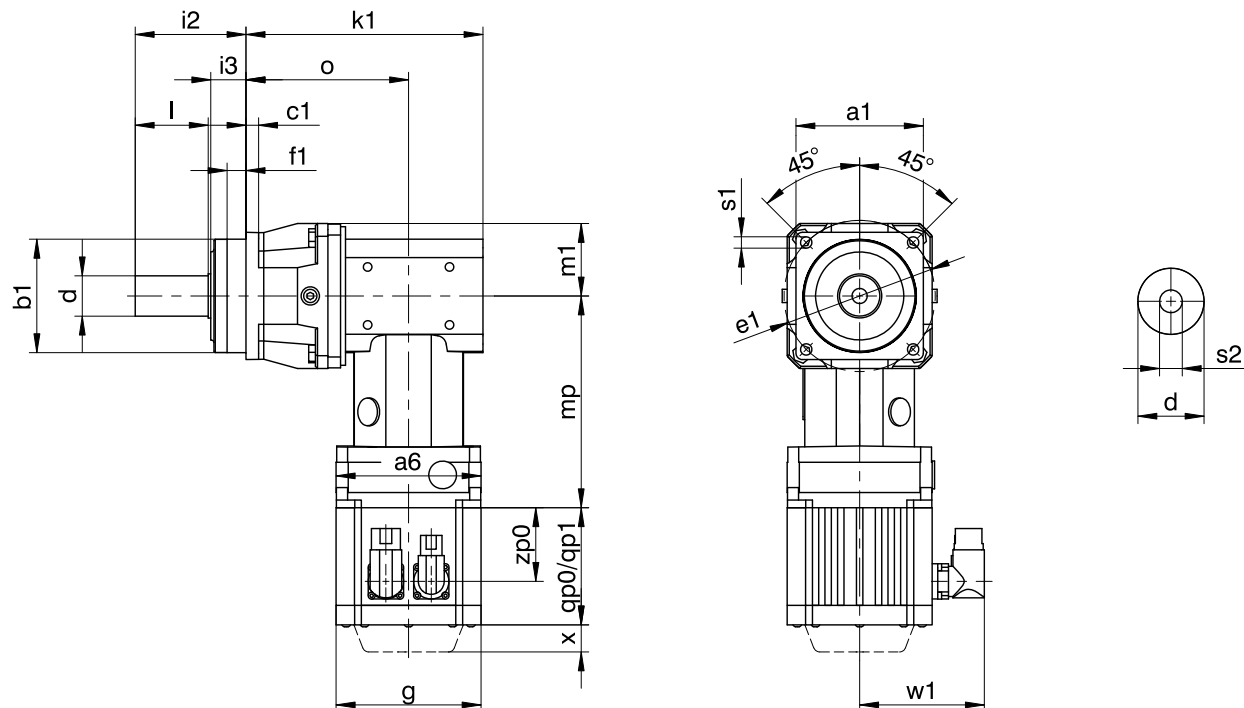
Solid shaft	Tolerance
Fit of shaft end $\varnothing \leq 50$ mm	DIN 748-1, ISO k6
Fit of shaft end $\varnothing > 50$ mm	DIN 748-1, ISO m6
Feather keys	DIN 6885-1, high form A
Balance quality	Q 2.5 (balanced with half feather key)

Centering holes in solid shafts in accordance with DIN 332-2, DR form

Thread size	M4	M5	M6	M8	M10	M12	M16	M20	M24
Gewindetiefe	10	12.5	16	19	22	28	36	42	50



14.3.1 G shaft design (solid shaft without feather key)



qp0	Applies to motors without brake.	qp1	Applies to motors with brake.
x	Applies to encoders using an optical measuring concept.	w1	For variation for One Cable Solution (OCS), see Chapter [22.4]

Dimensions of gear units

Type	□a1	∅b1	c1	∅d	∅e1	f1	i2	i3	k1	l	m1	o	∅s1	s2
P221_KX301_	55	50 _{h6}	6	12 _{k6}	63	7.0	36	12	124.0	22	31.0	84.0	5.5	M4
P321_KX301_	72	60 _{h6}	7	16 _{k6}	75	7.5	48	18	136.0	28	36.0	96.0	5.5	M5
P322_KX301_	72	60 _{h6}	7	16 _{k6}	75	7.5	48	18	176.0	28	36.0	136.0	5.5	M5
P421_KX401_	76	70 _{h6}	9	22 _{k6}	85	7.5	56	18	163.0	36	49.0	113.0	6.6	M8
P422_KX301_	76	70 _{h6}	9	22 _{k6}	85	7.5	56	18	193.5	36	49.0	153.5	6.6	M8
P521_KX501_	101	90 _{h6}	10	32 _{k6}	120	15.0	88	28	188.0	58	57.0	129.0	9.0	M12
P522_KX401_	101	90 _{h6}	10	32 _{k6}	120	15.0	88	28	220.5	58	57.0	170.5	9.0	M12
P721_KX701_	145	130 _{h6}	15	40 _{k6}	165	3.5	112	27	231.0	82	72.5	157.0	11.0	M16
P722_KX501_	145	130 _{h6}	15	40 _{k6}	165	3.5	112	27	265.0	82	72.5	206.0	11.0	M16
P821_KX801_	190	160 _{h6}	15	55 _{k6}	215	10.0	112	27	305.0	82	95.0	213.0	13.5	M20
P822_KX701_	190	160 _{h6}	15	55 _{k6}	215	10.0	112	27	339.5	82	95.0	265.5	13.5	M20
P922_KX801_	212	180 _{h6}	17	75 _{k6}	250	10.0	143	34	432.0	105	112.5	340.0	17.5	M20



Dimensions of motors

Type	□g	qp0	qp1	w1	x	zp0
EZ301U	72	90	130.0	55.5	21	54.5
EZ302U	72	112	152.0	55.5	21	76.5
EZ303U	72	134	174.0	55.5	21	98.5
EZ401U	98	98	146.5	91.0	22	56.0
EZ402U	98	123	171.5	91.0	22	81.0
EZ404U	98	173	221.5	91.0	22	131.0
EZ501U	115	93	147.5	100.0	22	58.5
EZ502U	115	118	172.5	100.0	22	83.5
EZ503U	115	143	197.5	100.0	22	108.5
EZ505U	115	193	247.5	100.0	22	158.5
EZ701U	145	102	161.0	115.0	22	64.0
EZ702U	145	127	186.0	115.0	22	89.0
EZ703U	145	152	211.0	115.0	22	114.0
EZ705U	145	207	266.0	134.0	22	165.0
EZ802U	190	197	274.0	156.5	22	143.0
EZ803U	190	238	315.0	156.5	22	184.0
EZ805U	190	320	397.0	156.5	22	266.0

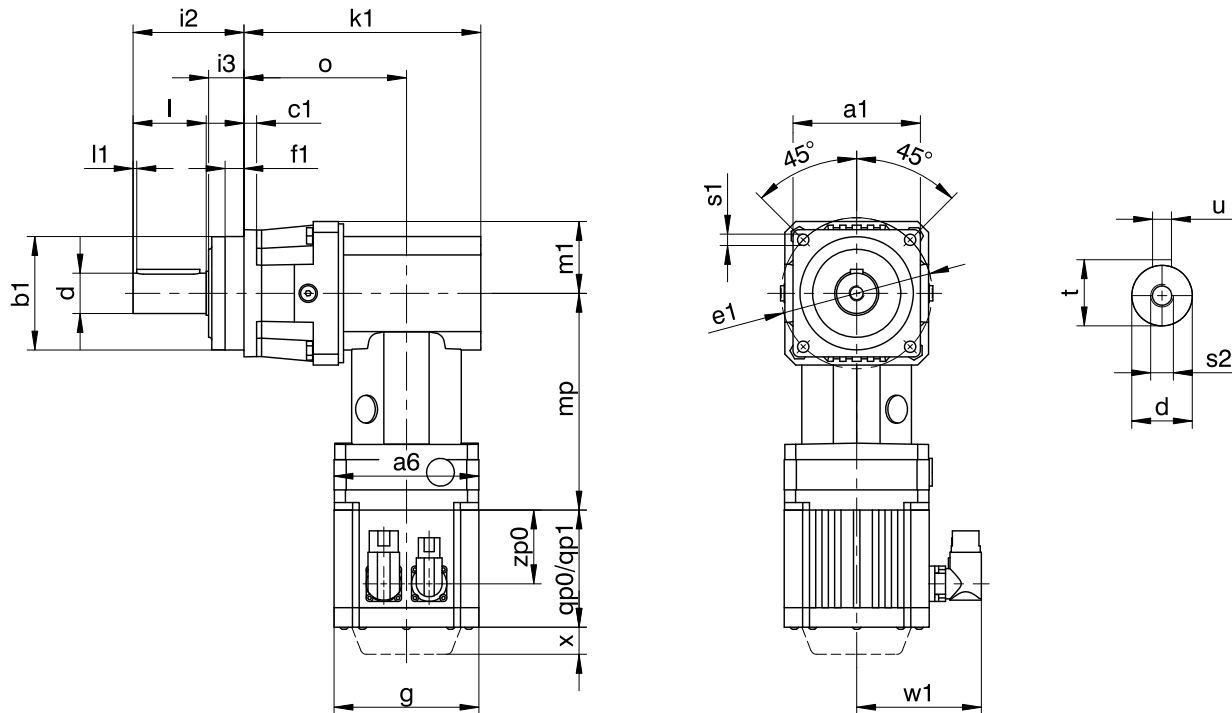
Dimensions of geared motors

Type	EZ3		EZ4		EZ5		EZ7		EZ8	
	□a6	mp	□a6	mp	□a6	mp	□a6	mp	□a6	mp
P221_KX301_	75	139.5	100	134.0	-	-	-	-	-	-
P321_KX301_	75	139.5	100	134.0	-	-	-	-	-	-
P322_KX301_	75	139.5	-	-	-	-	-	-	-	-
P421_KX401_	100	151.0	100	145.5	115	150.0	140	153.0	-	-
P422_KX301_	75	139.5	100	134.0	-	-	-	-	-	-
P521_KX501_	-	-	115	176.5	140	172.0	115	183.0	-	-
P522_KX401_	100	151.0	100	145.5	115	150.0	-	-	-	-
P721_KX701_	-	-	-	-	145	214.5	190	217.5	145	242.5
P722_KX501_	-	-	115	176.5	140	172.0	115	183.0	-	-
P821_KX801_	-	-	-	-	-	-	190	263.0	190	269.0
P822_KX701_	-	-	-	-	145	214.5	190	217.5	145	242.5
P922_KX801_	-	-	-	-	-	-	190	263.0	190	269.0

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14.3.2 P shaft design (solid shaft with feather key)



qp0	Applies to motors without brake.	qp1	Applies to motors with brake.
x	Applies to encoders using an optical measuring concept.	w1	For variation for One Cable Solution (OCS), see Chapter [22.4]

Dimensions of gear units

Type	□a1	Øb1	c1	Ød	Øe1	f1	i2	i3	k1	l	l1	m1	o	Øs1	s2	t	u
P221_KX301_	55	50 _{h6}	6	12 _{k6}	63	7.0	36	12	124.0	22	2	31.0	84.0	5.5	M4	13.5	A4x4x18
P321_KX301_	72	60 _{h6}	7	16 _{k6}	75	7.5	48	18	136.0	28	2	36.0	96.0	5.5	M5	18.0	A5x5x22
P322_KX301_	72	60 _{h6}	7	16 _{k6}	75	7.5	48	18	176.0	28	2	36.0	136.0	5.5	M5	18.0	A5x5x22
P421_KX401_	76	70 _{h6}	9	22 _{k6}	85	7.5	56	18	163.0	36	3	49.0	113.0	6.6	M8	24.5	A6x6x28
P422_KX301_	76	70 _{h6}	9	22 _{k6}	85	7.5	56	18	193.5	36	3	49.0	153.5	6.6	M8	24.5	A6x6x28
P521_KX501_	101	90 _{h6}	10	32 _{k6}	120	15.0	88	28	188.0	58	3	57.0	129.0	9.0	M12	35.0	A10x8x50
P522_KX401_	101	90 _{h6}	10	32 _{k6}	120	15.0	88	28	220.5	58	3	57.0	170.5	9.0	M12	35.0	A10x8x50
P721_KX701_	145	130 _{h6}	15	40 _{k6}	165	3.5	112	27	231.0	82	4	72.5	157.0	11.0	M16	43.0	A12x8x70
P722_KX501_	145	130 _{h6}	15	40 _{k6}	165	3.5	112	27	265.0	82	4	72.5	206.0	11.0	M16	43.0	A12x8x70
P821_KX801_	190	160 _{h6}	15	55 _{k6}	215	10.0	112	27	305.0	82	6	95.0	213.0	13.5	M20	59.0	A16x10x70
P822_KX701_	190	160 _{h6}	15	55 _{k6}	215	10.0	112	27	339.5	82	6	95.0	265.5	13.5	M20	59.0	A16x10x70
P922_KX801_	212	180 _{h6}	17	75 _{k6}	250	10.0	143	34	432.0	105	7	112.5	340.0	17.5	M20	79.5	A20x12x90



Dimensions of motors

Type	□g	qp0	qp1	w1	x	zp0
EZ301U	72	90	130.0	55.5	21	54.5
EZ302U	72	112	152.0	55.5	21	76.5
EZ303U	72	134	174.0	55.5	21	98.5
EZ401U	98	98	146.5	91.0	22	56.0
EZ402U	98	123	171.5	91.0	22	81.0
EZ404U	98	173	221.5	91.0	22	131.0
EZ501U	115	93	147.5	100.0	22	58.5
EZ502U	115	118	172.5	100.0	22	83.5
EZ503U	115	143	197.5	100.0	22	108.5
EZ505U	115	193	247.5	100.0	22	158.5
EZ701U	145	102	161.0	115.0	22	64.0
EZ702U	145	127	186.0	115.0	22	89.0
EZ703U	145	152	211.0	115.0	22	114.0
EZ705U	145	207	266.0	134.0	22	165.0
EZ802U	190	197	274.0	156.5	22	143.0
EZ803U	190	238	315.0	156.5	22	184.0
EZ805U	190	320	397.0	156.5	22	266.0

Dimensions of geared motors

Type	EZ3		EZ4		EZ5		EZ7		EZ8	
	□a6	mp	□a6	mp	□a6	mp	□a6	mp	□a6	mp
P221_KX301_	75	139.5	100	134.0	-	-	-	-	-	-
P321_KX301_	75	139.5	100	134.0	-	-	-	-	-	-
P322_KX301_	75	139.5	-	-	-	-	-	-	-	-
P421_KX401_	100	151.0	100	145.5	115	150.0	140	153.0	-	-
P422_KX301_	75	139.5	100	134.0	-	-	-	-	-	-
P521_KX501_	-	-	115	176.5	140	172.0	115	183.0	-	-
P522_KX401_	100	151.0	100	145.5	115	150.0	-	-	-	-
P721_KX701_	-	-	-	-	145	214.5	190	217.5	145	242.5
P722_KX501_	-	-	115	176.5	140	172.0	115	183.0	-	-
P821_KX801_	-	-	-	-	-	-	190	263.0	190	269.0
P822_KX701_	-	-	-	-	145	214.5	190	217.5	145	242.5
P922_KX801_	-	-	-	-	-	-	190	263.0	190	269.0

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14.4 Type designation

In this chapter, you can find an explanation of the type designation with the associated options. Additional ordering information not included in the type designation can be found at the end of the chapter.

Sample code

P	7	2	1	S	G	R	0050	KX701VF	0030	MF	EZ703U
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Explanation

Code	Designation	Design
P	Type	Planetary gear unit
7	Size	7 (example)
2	Generation	Generation 2
1	Stages	Single-stage
2		Two-stage
S	Housing	Standard
G	Shaft	Solid shaft without feather key
P		Solid shaft with feather key
R	Bearing	Standard bearing
D		Axially reinforced bearing
Z		Radially reinforced bearing
0050	Transmission ratio of output (i x 10)	i = 5 (example)
KX701 VF	Input	KX7 right-angle geared motor (example)
0030	Transmission ratio of input (i x 10)	i = 3 (example)
MF	Attachment to EZ	MF motor adapter
EZ703U	Motor	EZ synchronous servo motor

In order to complete the type designation, also specify:

- A detailed type designation of the motor, see Chapter [\[22\]](#)
- The installation position, see Chapter [\[14.5.2\]](#)
- Radial shaft seal rings at the output made of FKM or NBR, see Chapter [\[14.6.3\]](#)
- The position of the plug connectors, see Chapter [\[14.5.4\]](#)
- For reverse operation of the output shaft at $\pm 20^\circ$ to $\pm 90^\circ$ and horizontal installation, note Chapter [\[14.6.4\]](#)

14.5 Product description

14.5.1 Installation conditions

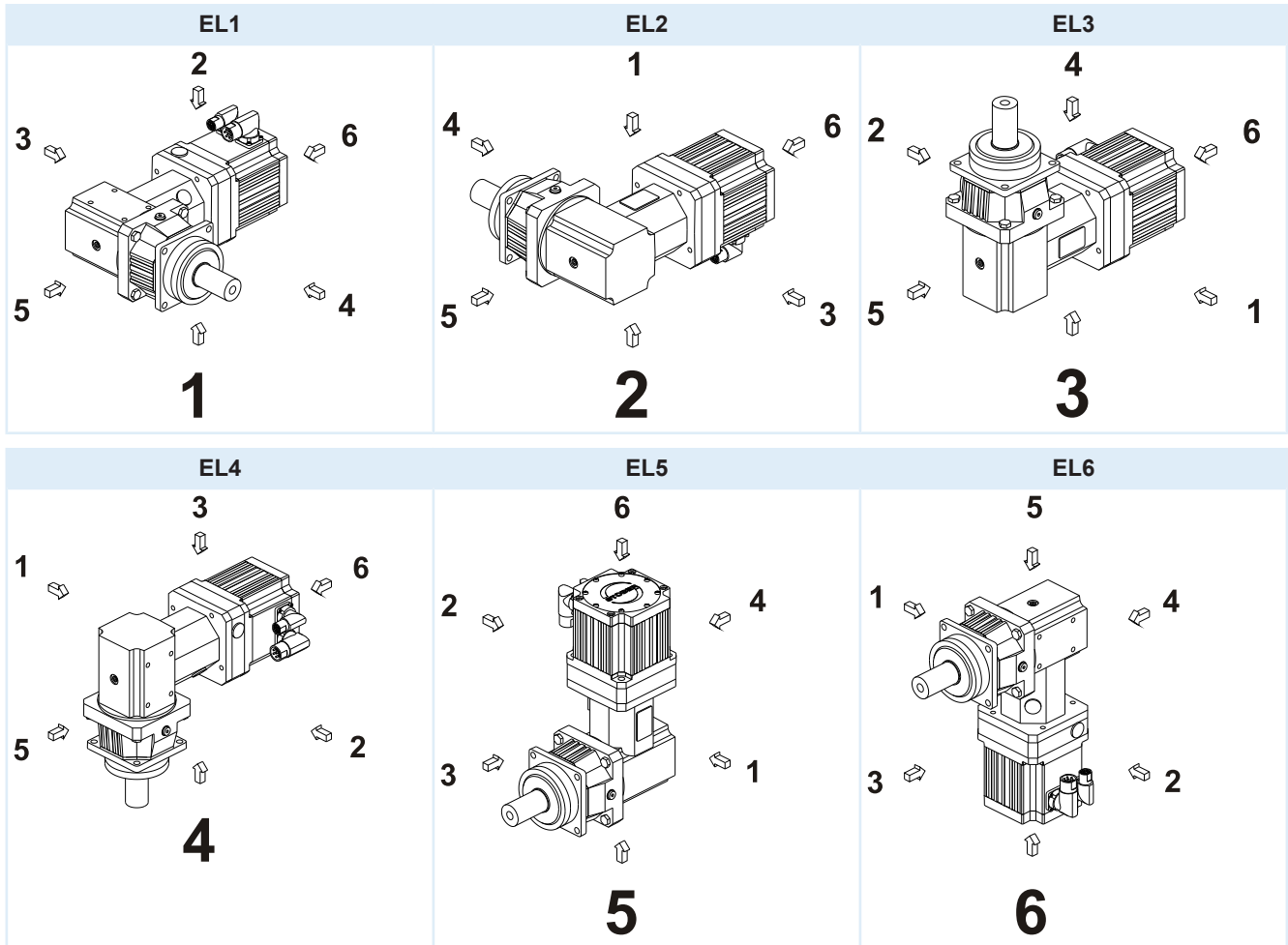
The specified torques and forces only apply when attaching gear units at the machine side using screws of quality 10.9. In addition, the gear housing must be adjusted at the pilot (H7).

14.5.2 Installation positions

The following table shows the standard installation positions.



The numbers identify the gear unit sides. The installation position is defined by the gear side facing downwards.



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Since the lubricant filling volume of the gear unit depends on the installation position, the installation position must be specified when ordering.

14.5.3 Lubricants

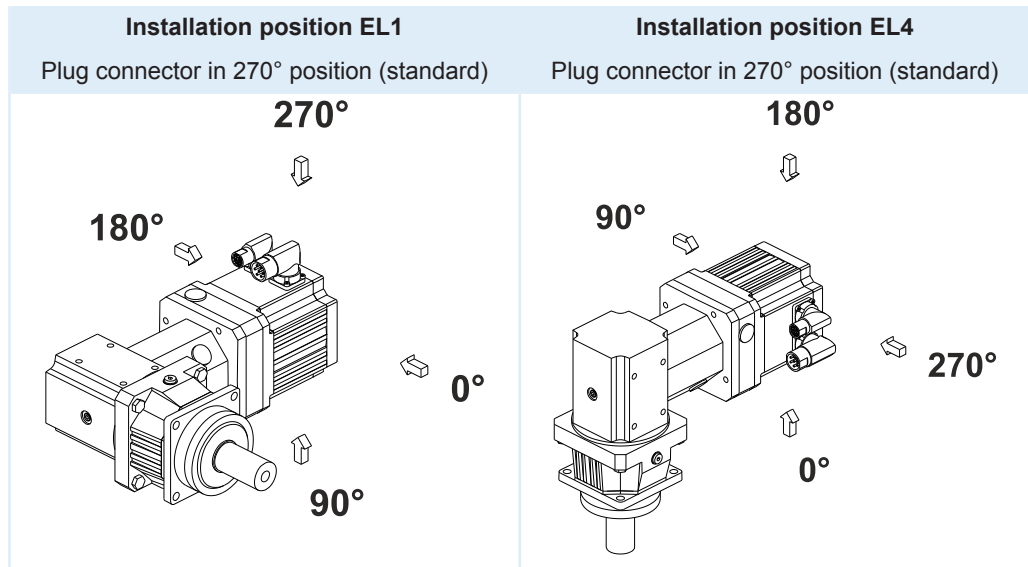
STOBER fills the gear units with the amount and type of lubricant specified on the nameplate. The filling volume and the structure of the gear units depend on the installation position.

Only install the gear units in the intended installation position! Reposition the gear units only after consulting STOBER. Otherwise, STOBER assumes no liability for the gear units.

Lubricant filling quantities for gear units, document ID 441871, can be found online at <http://www.stoeber.de>



14.5.4 Position of the plug connectors



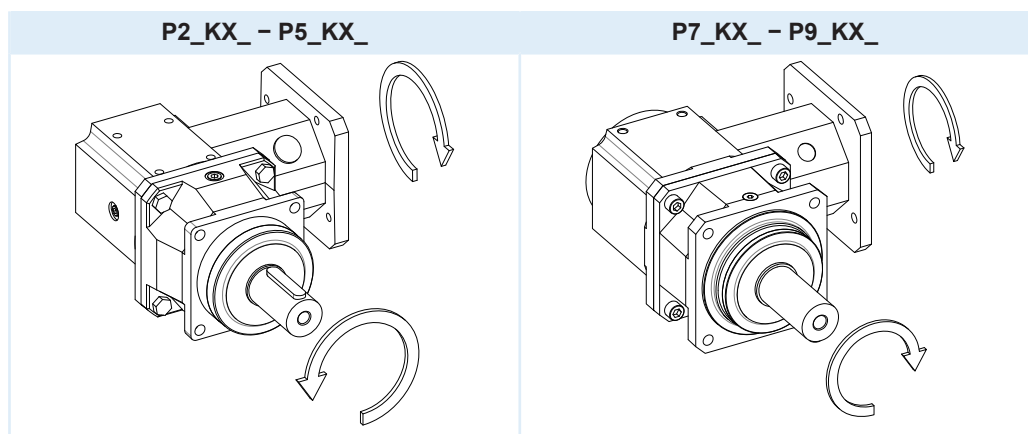
Indicate variations for your geared motor in the purchase order.

Note that the plug connector position rotates along with the geared motor if the geared motor is in another installation position.

14.5.5 Other product features

Feature	Value
Max. permitted gear unit temperature (on the surface of the gear unit)	≤ 90 °C
Paint	Black RAL 9005
(ATEX) Directive 2014/34/EU	Not suitable
Protection class: ¹	
Gear unit	IP65
Motor	IP56, optionally IP66

14.5.6 Direction of rotation



The pictures show installation position EL1.

¹ Observe the protection class of all the components.



14.6 Project configuration

Project your drive using our SERVOfsoft designing software. You can receive SERVOfsoft for free from your adviser at one of our sales centers. Observe the limit conditions in this chapter to ensure a safe design for your drives.

The formula symbols for values actually present in the application are marked with *.

Formula symbol	Unit	Explanation
a_{th}	–	Parameter for calculating $K_{mot,th}$
a_{thEL}	–	Parameters for calculating $K_{mot,th}$ (dependent on the installation position)
ED	%	Duty cycle relative to 20 minutes
fB_{op}	–	Operating mode operating factor
fB_t	–	Run-time operating factor
fB_T	–	Temperature operating factor
F_{2ax}^*	N	Actual axial force at the gear unit output
F_{2ax100}	N	Permitted axial force at the gear unit output for $n_{2m} \leq 100$ rpm
F_{2axN}	N	Permitted nominal axial force at the gear unit output
$F_{2rad,acc}$	N	Permitted radial acceleration force at the gear unit output
$F_{2rad,acc}^*$	N	Actual radial acceleration force at the gear unit output
$F_{2rad,acc,1}^*$	N	Actual radial acceleration force at the gear unit output in the first time segment
$F_{2rad,acc,n}^*$	N	Actual radial acceleration force at the gear unit output in the n-th time segment
$F_{2rad,eq}^*$	N	Actual equivalent force at the gear unit output
$F_{2rad100}$	N	Permitted radial force at the gear unit output for $n_{2m} \leq 100$ rpm
F_{2radN}	N	Permitted nominal radial force at the gear unit output
i	–	Gear ratio
$K_{mot,th}$	–	Factor for determining the thermal limit torque
l	mm	Length of the output shaft
L_{10h}	h	Bearing service life
M_{op}	Nm	Torque of motor at the operating point from the motor characteristic curve at n_{1m}^*
$ M_2 $	Nm	Amount of torque on the output
$M_{2,1}^* - M_{2,6}^*$	Nm	Actual torque in the respective time segment (1 to 6)
$M_{2,n}^*$	Nm	Actual torque in the n-th time segment
M_{2acc}	Nm	Maximum permitted acceleration torque on the gear unit output
M_{2acc}^*	Nm	Actual acceleration torque on the gear unit output
M_{2eff}^*	Nm	Actual effective torque on the gear unit output
M_{2eq}^*	Nm	Equivalent torque present on the gear unit output
M_{2k100}	Nm	Permitted breakdown torque on the gear unit output for $n_{2m} \leq 100$ rpm
M_{2kN}	Nm	Permitted nominal breakdown torque on the gear unit output
M_{2k}^*	Nm	Actual breakdown torque on the gear unit output
$M_{2k,acc}$	Nm	Permitted acceleration breakdown torque on the gear unit output
$M_{2k,acc}^*$	Nm	Actual acceleration breakdown torque on the gear unit output



Formula symbol	Unit	Explanation
$M_{2k,acc,1^*}$	Nm	Actual acceleration breakdown torque on the gear unit output in the first time segment
M_{2k,acc,n^*}	Nm	Actual acceleration breakdown torque on the gear unit output in the n-th time segment
M_{2k,eq^*}	Nm	Actual equivalent breakdown torque on the gear unit output
M_{2N}	Nm	Nominal torque on the gear unit output (relative to n_{1N})
M_{2NOT}	Nm	Gear unit emergency-off torque on the gear unit output for max. 1000 load changes
M_{2NOT^*}	Nm	Actual emergency off torque for the gear unit on the gear unit output
M_{2th}	Nm	Thermal limit torque on the gear unit output
n_{1m^*}	rpm	Actual average input speed
n_{1max^*}	rpm	Actual maximum input speed
$n_{1maxDBEL1,2,5,6}$	rpm	Maximum permitted input speed of the gear unit in continuous operation Installation positions EL1, EL2, EL5, EL6
$n_{1maxDBEL3,4}$	rpm	Maximum permitted input speed of the gear unit in continuous operation Installation positions EL3, EL4
n_{1maxZB}	min ⁻¹	Maximum permitted input speed of the gear unit in cyclic operation
$ n_2 $	rpm	Value of output speed
n_{2m^*}	rpm	Actual average output speed
$n_{2m,1^*} - n_{2m,6^*}$	rpm	Actual average output speed in the respective time segment (1 to 6)
n_{2m,n^*}	rpm	Actual average output speed in the n-th time segment
t	s	Time
$t_1^* - t_6^*$	s	Duration of the respective time segment (1 to 6)
t_n^*	s	Duration of the n-th time segment
S	–	Load value: Quotient of gear unit and motor nominal torque without regard to the thermal performance limit. Represents a value for the reserve of the geared motor.
x_2	mm	Distance of the shaft shoulder to the force application point
y_2	mm	Distance of the shaft axis to the axial force application point
z_2	mm	Distance of the shaft shoulder to the middle of the output bearing

14.6.1 Calculation of the operating point

Check the following conditions for operating points other than the nominal point M_{2N} specified in the selection tables.

For installation positions EL1, EL2, EL5, EL6:

$$n_{1m^*} \leq \frac{n_{1maxDBEL1,2,5,6}}{fB_T}$$

For installation positions EL3, EL4:

$$n_{1m^*} \leq \frac{n_{1maxDBEL3,4}}{fB_T}$$



$$n_{1\max} \leq \frac{n_{1\max ZB}}{fB_T}$$

$$M_{2\text{eff}} \leq M_{2\text{th}}$$

$$M_{2\text{acc}} \leq M_{2\text{acc}}$$

$$M_{2\text{NOT}} \leq M_{2\text{NOT}}$$

$$M_{2\text{eq}} \leq M_{2N} \cdot \frac{S}{fB_{\text{op}} \cdot fB_t}$$

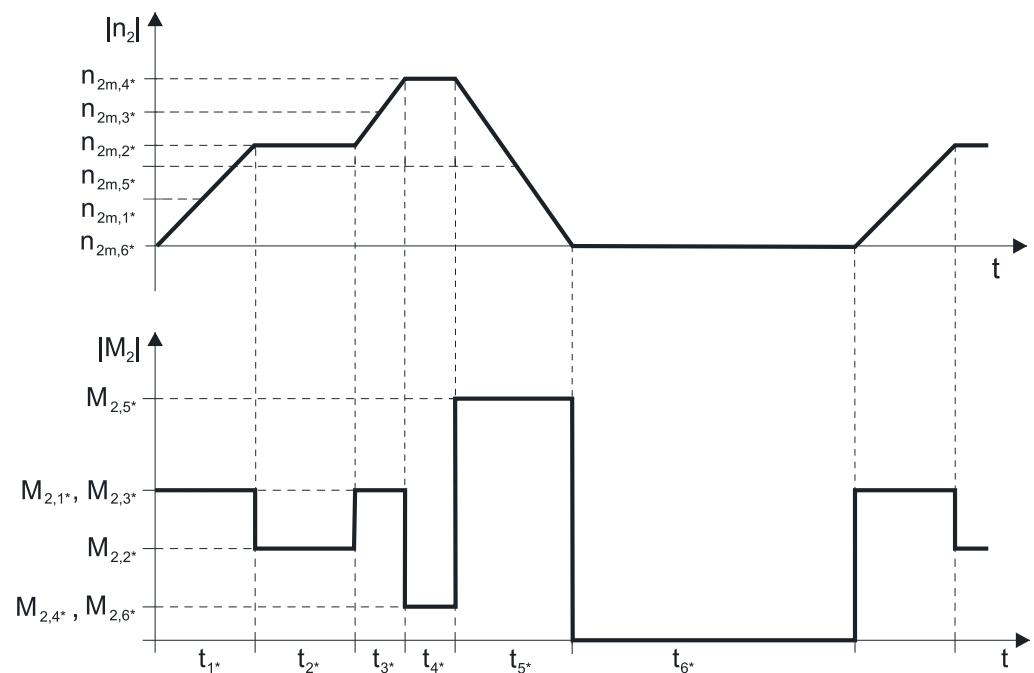
The values for $n_{1\max DBEL1,2,5,6}$, $n_{1\max DBEL3,4}$, $n_{1\max ZB}$, $M_{2\text{acc}}$, $M_{2\text{NOT}}$, M_{2N} and S can be found in the selection tables.

The values for fB_T , fB_{op} and fB_t can be found in the corresponding tables in this chapter.

Calculate the thermal limit torque $M_{2\text{th}}$ for a duty cycle > 50%.

Example of cycle sequence

The following calculations are based on a representation of the power taken from the output based in accordance with the following example:



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Calculation of the actual average input speed

$$n_{1m} = n_{2m} \cdot i$$

$$n_{2m} = \frac{|n_{2m,1}| \cdot t_1 + \dots + |n_{2m,n}| \cdot t_n}{t_1 + \dots + t_n}$$

If $t_1 + \dots + t_5 \geq 20$ min, calculate n_{2m} without the rest phase t_6 .

The values for the ratio i can be found in the selection tables.

Calculation of the actual effective torque

$$M_{2\text{eff}} = \sqrt{\frac{t_1 \cdot M_{2,1}^2 + \dots + t_n \cdot M_{2,n}^2}{t_1 + \dots + t_n}}$$



Calculation of the actual equivalent torque

$$M_{2eq*} = \sqrt[3]{\frac{|n_{2m,1*} \cdot t_{1*} \cdot M_{2,1*}^3 + \dots + |n_{2m,n*} \cdot t_{n*} \cdot M_{2,n*}^3|}{|n_{2m,1*} \cdot t_{1*} + \dots + |n_{2m,n*} \cdot t_{n*}|}}$$

Calculation of the thermal limit torque

Calculate the thermal limit torque M_{2th} for a duty cycle $ED > 50\%$ and the actual average input speed n_{1m*} . (At $K_{mot,th} \leq 0$ you must reduce the average input speed n_{1m*} accordingly or select another geared motor size.)

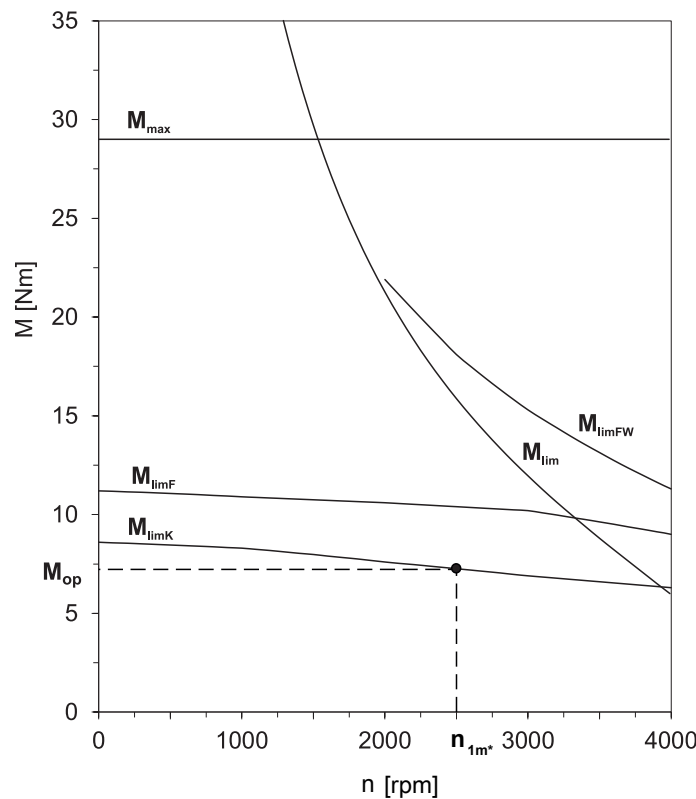
$$M_{2th} = M_{op} \cdot i \cdot K_{mot,th}$$

$$K_{mot,th} = 0,9 - \frac{a_{th}}{1000} \cdot athEL \cdot fB_T \cdot \left(\frac{n_{1m*}}{1000}\right)^3$$

The values for i and a_{th} can be found in the selection tables.

The values for a_{thEL} and fB_T can be found in the corresponding tables in this chapter.

The value for the torque of the motor at operating point M_{op} with the determined average input speed n_{1m*} can be found in the motor curve of Chapter [22.3]. Note the size, nominal speed n_N and cooling type of the motor. The figure below shows an example of reading the torque M_{op} of a motor with convection cooling at the operating point.



Operating factors

Parameter a_{thEL}

Installation position	a_{thEL}
EL1, 2, 5, 6	1.0
EL3, 4	1.1



Operating mode		fB_{op}
Uniform continuous operation		1.00
Cyclic operation		1.25
Reversing load cyclic operation		1.40
Run time		fB_t
Daily run time ≤ 8 h		1.00
Daily run time ≤ 16 h		1.15
Daily run time ≤ 24 h		1.20
Temperature		fB_T
Motor cooling	Surrounding temperature	
Motor with forced ventilation	≤ 20 °C	0.9
	≤ 30 °C	1.0
	≤ 40 °C	1.15
Motor with convection cooling	≤ 20 °C	1.0
	≤ 30 °C	1.1
	≤ 40 °C	1.25

Notes

- The maximum permitted gear unit temperature (see the "Other product features" chapter) must not be exceeded. Doing so may result in damage to the geared motor.
- For braking from full speed (for example when the power fails or when setting up the machine), note the permitted gear unit torques (M_{2acc} , M_{2NOT}) in the selection tables.
- The values specified in the selection tables for M_{2acc} refer to the gear units with a solid shaft design without feather key (G). We recommend this shaft design in general for cyclic operation.

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14.6.2 Permitted shaft loads for the output shaft

The values specified in the tables apply to the permitted shaft loads:

- For shaft dimensions in accordance with the catalog
- For output speeds $n_{2m} \leq 100$ rpm ($F^{2axN} = F_{2ax100}$; $F_{2radN} = F_{2rad100}$; $M_{2kN} = M_{2k100}$)
- Only if transverse forces on the gear unit are supported via its pilots (housing, flange shaft)

Permitted shaft loads for standard bearing R

Type	z_2 [mm]	F_{2ax100} [N]	$F_{2rad100}$ [N]	$F_{2rad,acc}$ [N]	M_{2k100} [Nm]	$M_{2k,acc}$ [Nm]
P2	17.0	500	1200	1300	34	36
P3	21.0	1000	2500	2500	88	88
P4	22.0	1500	4000	4500	160	180
P5	23.0	2300	6500	7000	338	364
P7	26.0	2900	8000	9000	536	603
P8	28.0	4700	13000	18000	897	1242
P9	40.0	6000	18000	27000	1665	2498

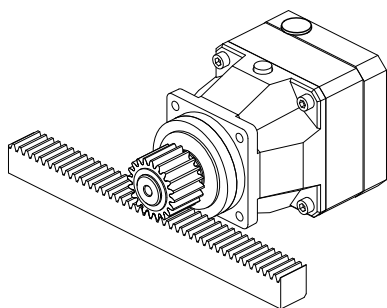


Fig. 1: Recommendation for bearing assignment R

Permitted shaft loads for axially reinforced bearing D

Type	z_2 [mm]	F_{2ax100} [N]	$F_{2rad100}$ [N]	$F_{2rad,acc}$ [N]	M_{2k100} [Nm]	$M_{2k,acc}$ [Nm]
P3	24.0	1400	2750	2750	105	105
P4	25.0	2250	4500	5000	194	215
P5	29.0	3500	7000	8000	406	464
P7	31.0	4500	9000	10000	648	720
P8	35.0	7500	15000	18000	1140	1368
P9	51.0	10000	20000	30000	2070	3105

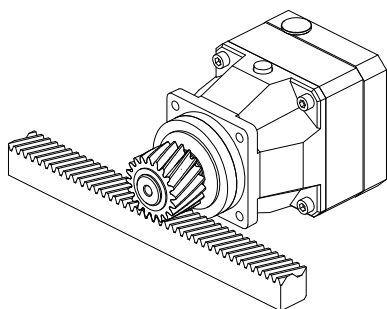


Fig. 2: Recommendation for bearing assignment D

Permitted shaft loads for radially reinforced bearing Z

Type	z_2 [mm]	F_{2ax100} [N]	$F_{2rad100}$ [N]	$F_{2rad,acc}$ [N]	M_{2k100} [Nm]	$M_{2k,acc}$ [Nm]
P3	21.0	600	3000	3000	105	105
P4	22.0	1000	5000	5000	200	200
P5	23.0	1600	8000	8000	416	416
P7	26.0	2000	10000	10000	670	670
P8	28.0	3600	18000	18000	1242	1242
P9	40.0	5000	27000	35000	2500	3238

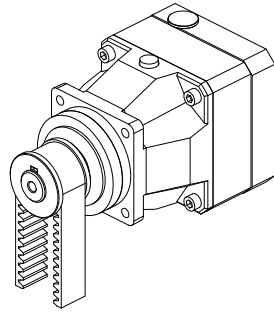


Fig. 3: Recommendation for bearing assignment Z

For other output speeds, download diagrams at <http://products.stoeber.de>.

The following applies to output speeds $n_{2m^*} > 100$ rpm:

$$F_{2axN} = \frac{F_{2ax100}}{\sqrt[3]{\frac{n_{2m^*}}{100 \text{ rpm}}}} \quad F_{2radN} = \frac{F_{2rad100}}{\sqrt[3]{\frac{n_{2m^*}}{100 \text{ rpm}}}} \quad M_{2kN} = \frac{M_{2k100}}{\sqrt[3]{\frac{n_{2m^*}}{100 \text{ rpm}}}}$$

The values for F_{2ax100} , $F_{2rad100}$ and M_{2k100} can be found in the table "Permitted shaft loads" in this chapter.

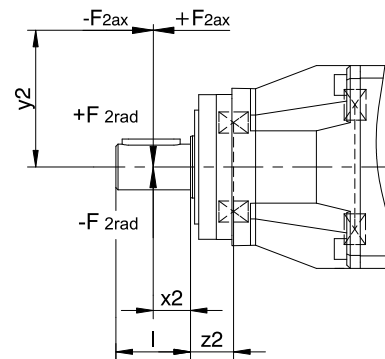


Fig. 4: Force application points

The specified values for $F_{2rad100}$ and $F_{2rad,acc}$ refer to an application of force at the center of the output shaft: $x_2 = l/2$.

Shaft dimensions can be found in the "Dimensional drawings" chapter.

The following applies to other force application points:

$$M_{2k,acc^*} = \frac{2 \cdot F_{2ax^*} \cdot y_2 + F_{2rad,acc^*} \cdot (x_2 + z_2)}{1000} \leq M_{2k,acc}$$

$$F_{2rad,acc^*} \leq F_{2rad,acc}$$

$$F_{2ax^*} \leq F_{2axN}$$

The values for $F_{2rad,acc}$ and $M_{2k,acc}$ can be found in the table "Permitted shaft loads" in this chapter.

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax100} , $F_{2rad100}$ and M_{2k100} by a factor of two.



Also note the calculation for equivalent values:

$$M_{2k,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |M_{2k,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |M_{2k,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}} \leq M_{2kN}$$

$$F_{2rad,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |F_{2rad,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |F_{2rad,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}} \leq F_{2radN}$$

The following apply to the bearing service life L_{10h} (duty cycle $\leq 40\%$):

$$L_{10h} > 10000 \text{ h with } 1 < M_{2kN}/M_{2k^*} < 1.25$$

$$L_{10h} > 20000 \text{ h with } 1.25 < M_{2kN}/M_{2k^*} < 1.5$$

$$L_{10h} > 30000 \text{ h with } 1.5 < M_{2kN}/M_{2k^*}$$

For different duty cycles:

$$L_{10h} > L_{10h(ED=40\%)} \cdot \frac{40\%}{ED}$$

14.6.3 Recommendation for radial shaft seal rings

For a duty cycle $> 60\%$, we recommend radial shaft seal rings made of FKM.

Properties:

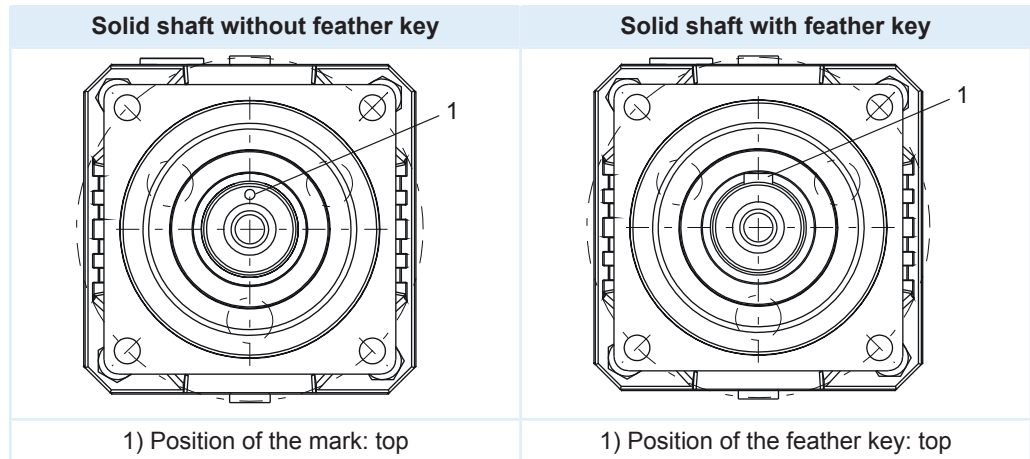
- Excellent temperature resistance
- High chemical stability
- Very good resistance to aging
- Excellent resistance to mineral oils and greases
- For use in the food, beverage and pharmaceutical industries

Leak-proofness

Our gear units are equipped with high-quality radial shaft seal rings and checked for leak-proofness. However, a leak cannot be fully ruled out over the length of use of the gear unit. If you use the gear unit with goods incompatible with the lubricant, you must take measures to prevent direct contact with the gear unit lubricant in case of a leak.

14.6.4 Reverse operation

To ensure lubrication of circulating geared parts during cyclic reverse operation from $\pm 20^\circ$ to $\pm 90^\circ$, pay careful attention to the position of the output shaft if the gear unit is installed horizontally as shown in the images below. The images show the center position of reverse operation. Cyclic reverse operation $\leq \pm 20^\circ$ on request.



Notes

- If you use the solid shaft without a feather key (G) with a mark, note the position of the mark during assembly.
- As an alternative, you can use the solid shaft with a feather key (P) and clamp. In that case, the feather key functions for position orientation.

14.7 Additional documentation

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Additional documentation related to the product can be found at <http://www.stoeber.de/en/download>

Enter the ID of the documentation in the Search... field.

Documentation	ID
Operating manual for planetary gear units and motors	441957
Lubricant filling quantities for gear units	441871